

Fig. 4

WO 2005/080164 PCT/EP2005/050724

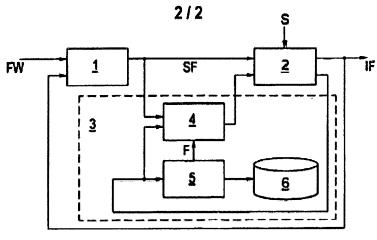


Fig. 2

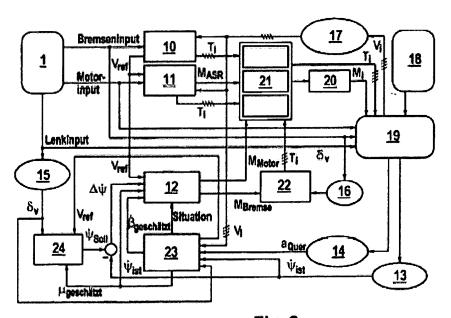


Fig. 3

Bremseinput	=	Brake input	Motor	=	Engine	Quer	=	Lateral
Motorinput	=	Engine input	Bremse	=	Brake	Soll	=	Theoretical
Lenkinput	=	Steering input	geschätzt	=	Estimated	ist	=	Actual

13